APPLICATIONS OF THE EULER
CHARACTERISTIC IN BIFURCATION THEORY

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Abstract

Let $f : \mathbb{R}^n \times \mathbb{R}^k \to \mathbb{R}^n$ be a continuous map such that $f(0, \lambda) = 0$ for all $\lambda \in \mathbb{R}^k$. In this article we formulate, in terms of the Euler characteristic of algebraic sets, sufficient conditions for the existence of bifurcation points of the equation $f(x, \lambda) = 0$. Moreover we apply these results in bifurcation theory to ordinary differential equations. It is worth to point out that in the last paragraph we show how to verify, by computer, the assumptions of the theorems of this paper.

0. Introduction

In [A] Alexander has defined an invariant which nontriviality implies the existence of a bifurcation point of a continuous map $f : \mathbb{R}^n \times \mathbb{R}^k \to \mathbb{R}^n$ such that $f(0, \lambda) = 0$ for all $\lambda \in \mathbb{R}^k$. This invariant is an element of the group $\pi_{k-1}(GL(n))$. Generally it is difficult to verify if this invariant is a nontrivial element in $\pi_{k-1}(GL(n))$.

Krasnosielski in [K] has proved a 1-parameter bifurcation theorem which is a very useful tool in bifurcation theory. This theorem gives sufficient conditions for the existence of a bifurcation point of $f$ in the case $k = 1$.

Many authors have proved generalizations of the classical Krasnosielski theorem (see [MA], [R1], [R2]).

We are interested in formulating sufficient conditions for the existence of bifurcation points of $f$ in case the dimension of the parameter space is greater than one and when the Alexander invariant can not be applied.

In [S1], [S2] and [W] the authors have proved very interesting formulas to a computation of the Euler characteristic of algebraic sets in terms of the Brouwer topological degree of suitable maps.

In the first part of this paper (using these formulas) we formulate and prove sufficient conditions for the existence of bifurcation points of $f$.

Namely, we define (Def. 1.4.) a set of essential maps (Ess $(n,k)$) and prove that $0 \in \mathcal{R}$ is not an isolated bifurcation point of any essential map $f$ (Prop. 1.1.).
We also define (Def. 1.3.) a set of regular maps \( \text{Reg}(n,k) \) and show how to verify if a regular map is an essential map (Prop. 1.3.).

In Proposition 1.4. we formulate sufficient condition for the existence of a bifurcation point of a homogeneous map \( f \) (for definition of a homogeneous map see Def. 1.2.).

As the last case we consider a set of even maps \( \text{Even}(n,k), \) Def. 1.5.). In Proposition 1.5. we give sufficient conditions for the existence of a bifurcation point of even map.

Notice that the assumptions of Propositions 1.4., 1.5., 1.6. are expressed in terms of the Brouwer topological degree of polynomial maps. From this point of view it is important to compute the Brouwer topological degree for polynomial maps.

Nierenberg has formulated in [N] an integral definition of the Brouwer topological degree. We have written a computer program which computes the topological degree for polynomial maps, in a version given by Nierenberg.

The important question is how to verify that \( f \in \text{Reg}(n,k) \). In other words we must verify if \( 0 \in \mathbb{R}^k \) is an isolated point in \( \Psi^{-1}(0) \). There are computer algorithms which allow us to check if \( 0 \in \mathbb{R}^k \) is an isolated zero of the polynomial map \( \Psi : \mathbb{R}^k \to \mathbb{R}^k \). These algorithms are based on the Eisenbud and Levine results (see [E.L.]). There is a computer program, written by Andrzej Lecki from University of Gdansk, which is based on such kinds of algorithms. Using this program we can verify if \( f \in \text{Reg}(n,k) \).

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In the second paragraph we apply topological results of this article to the bifurcation theory for ordinary differential equations (Th. 2.1., 2.2., 2.3.).

In the last part of this paper we show how to verify by computer the assumptions of the theorems of this paper.

1. Results

Denote by \( X \) and \( Y \) Banach spaces and by \( f : X \times \mathbb{R}^k \to Y \) a continuous operator such that \( f(0,\lambda) = 0 \) for all \( \lambda \in \mathbb{R}^k \).

**Definition 1.1.** A point \( \lambda_0 \in \mathbb{R}^k \) is said to be a bifurcation point of the equation (*) \( f(x,\lambda) = 0 \), if

\[
(0,\lambda_0) \in \text{closure}\{ (x,\lambda) \in X \times \mathbb{R}^k : f(x,\lambda) = 0 \text{ and } x \neq 0 \}.
\]

The set of bifurcation points of the equation (*) will be denoted by \( \text{Bif}(f) \).

Consider a \( C^1 \)-map \( f : \mathbb{R}^n \times \mathbb{R}^k \to \mathbb{R}^n \) such that \( f(0,\lambda) = 0 \) for all \( \lambda \in \mathbb{R} \) and define a map \( \Phi : \mathbb{R}^k \to \mathbb{R} \) by \( \Phi(\lambda) = \det(D_x f(0,\lambda)) \).

**Definition 1.2.** A map \( f \) is said to be a homogeneous map, if \( \Phi(\lambda) \) is a homogeneous polynomial of degree greater than 1.
The set of homogeneous maps will be denoted by $\text{Hom}(n,k)$.

**Definition 1.3.** A map $f : \mathbb{R}^n \times \mathbb{R}^k \to \mathbb{R}^n$ is said to be a regular map, if

1) $f \in \text{Hom}(n,k)$,

2) $\Phi$ has an isolated critical point at the origin.

The set of regular maps will be denoted by $\text{Reg}(n,k)$.

Define a map $\Psi : \mathbb{R}^k \to \mathbb{R}^k$ by the formula

$$\Psi(\lambda) = \left(\frac{\partial \Phi}{\partial \lambda_1}(\lambda)\right)^2 + \Phi(\lambda)^2, \ldots, \left(\frac{\partial \Phi}{\partial \lambda_k}(\lambda)\right)^2 + \Phi(\lambda)^2$$

and notice that if $\Psi(\lambda_0) = 0$, then $\Psi(t \cdot \lambda_0) = 0$ for all $t \in \mathbb{R}$.

**Remark 1.1.** The map $\Phi$ has an isolated critical point at the origin iff $\Psi^{-1}(0) = \{0\}$.

Using this remark we will show that a map considered in Example 3.2. is a regular map.

**Definition 1.4.** A map $f : \mathbb{R}^n \times \mathbb{R}^k \to \mathbb{R}^n$ is said to be an essential map, if

1) $f \in \text{Reg}(n,k)$,

2) $\Phi^{-1}(0) \neq \{0\}$.

The set of essential maps will be denoted by $\text{Ess}(n,k)$.

**Proposition 1.1.** If $f \in \text{Ess}(n,k)$, then $\text{Bif}(f) = \Phi^{-1}(0)$. In particular, $\text{Bif}(f) \neq \emptyset$.

**Proof:** The set $\Phi^{-1}(0) - \{0\}$ is a $(k-1)$-dimensional manifold.

Fix $\lambda_0 \in \Phi^{-1}(0) - \{0\}$ and 1-dimensional manifold $N(\lambda_0)$ such that manifolds $N(\lambda_0)$ and $\Phi^{-1}(0) - \{0\}$ are transversal at the point $\lambda_0$. It is easy to see that the map $\Phi$ changes sign, at the point $\lambda_0$, along $N(\lambda_0)$. So, applying Krasnoselski theorem (see [K]) we show that $\lambda_0 \in \text{Bif}(f)$. The set $\text{Bif}(f)$ is closed, that is why $0 \in \text{Bif}(f)$. ■

Denote by $d\Phi : \mathbb{R}^k \to \mathbb{R}^k$ the gradient of the map $\Phi$.

If $f \in \text{Reg}(n,k)$ then $d\Phi^{-1}(0) = \{0\}$. Denote by $\chi(B)$ the Euler characteristic of the manifold $B$ and by $\deg d\Phi$ the Brouwer topological degree of $d\Phi$ with respect to a disc centered at the origin.

**Proposition 1.2.** If $f \in \text{Ess}(n,k)$, then for any $\varepsilon > 0$

i) $\Phi^{-1}(0) \cap S_{\varepsilon}^{k-1}$ is a $(k-2)$-dimensional manifold,

ii) $\chi(\Phi^{-1}(0) \cap S_{\varepsilon}^{k-1}) = (1 + (-1)^k) \cdot (1 - \deg d\Phi)$.

**Proof:** Notice that $\Phi^{-1}(0) - \{0\}$ is a $(k-1)$-dimensional manifold transversal to $S_{\varepsilon}^{k-1}$. That is why $\Phi^{-1}(0) \cap S_{\varepsilon}^{k-1}$ is a $(k-2)$-dimensional manifold.

Let us put the following notations $A_+ = \{\lambda \in S_{\varepsilon}^{k-1} : \Phi(\lambda) \geq 0\}$, $A_- = \{\lambda \in S_{\varepsilon}^{k-1} : \Phi(\lambda) \leq 0\}$, $L = \{\lambda \in S_{\varepsilon}^{k-1} : \Phi(\lambda) = 0\}$.
C.T.C. Wall in [W] has shown that \( \chi(A_+) = 1 + (-1)^{k-1} \cdot \deg d\Phi \) and
\( \chi(A_-) = 1 - \deg d\Phi \).

It is well known that \( \chi(L) = \chi(A_+) + \chi(A_-) - \chi(S_{k-1}^\epsilon) \).

Using the above formula and C.T.C. Wall results we obtain the thesis. ■

Proposition 1.3. If \( f \in \text{Reg} (n, k) \) and \( (1 + (-1)^k) \cdot (1 - \deg d\Phi) \neq 0 \), then \( f \in \text{Ess} (n, k) \).

Proof: If \( f \in \text{Reg} (n, k) \), then \( \Phi^{-1}(0) \cap S_{k-1}^\epsilon \) is a \((k-2)\)-dimensional manifold
or is an empty set. From Proposition 1.2. and from the assumptions it follows
that \( \Phi^{-1}(0) \cap S_{k-1}^\epsilon \) is not empty set. So our proof is completed. ■

In this part of the paragraph we formulate sufficient conditions for the existence of bifurcation points, in a case when \( f \in \text{Hom} (n, k) \).

Let us denote \( B_i = \{ \lambda \in S_{k-1}^\epsilon : (-1)^{i+1} \cdot \Phi(\lambda) > 0 \} \) for \( i = 1, 2 \) and let \( m \) be
the degree of the polynomial \( \Phi(\lambda) \).

If \( m \) is an odd number then \( \Phi \) has to change a sign near the origin that is
why it is enough to consider only the case of even \( m \).

Define polynomials \( \Gamma_i : R^k \rightarrow R \) by the formula
\[
\Gamma_i(\lambda) = (-1)^i \Phi(\lambda) - \|\lambda\|^{m+2},
\]
for \( i = 1, 2 \). By \( d\Gamma_i : R^k \rightarrow R^k \) we denote the gradient of \( \Gamma_i \).

By \( \deg (Q, D_k^\epsilon, 0) \) we will denote the Brouwer topological degree of the map \( Q \) computed on the disc \( D_k^\epsilon \) with respect to the origin.

Proposition 1.4. There is a positive number \( \epsilon > 0 \) such that \( d\Gamma_i^{-1}(0) \cap D_k^\epsilon = \{0\} \). If \( \deg (d\Gamma_i, D_k^\epsilon, 0) \neq (-1)^k \) for \( i = 1, 2 \), then for any \( \epsilon_1 > 0 \) \( \text{Bif} (f) \cap S_{k-1}^\epsilon \neq \emptyset \), in particular, \( 0 \in \text{Bif} (f) \). Moreover the topological dimension of the set \( \text{Bif} (f) \cap S_{k-1}^\epsilon \) is equal to \( k - 2 \).

Proof: First of all we will show that \( \chi(B_i) \neq \chi(S_{k-1}^\epsilon) \) for \( i = 1, 2 \). Szafarz has shown in [S2] that there is \( \epsilon > 0 \) such that \( d\Gamma_i^{-1}(0) \cap D_k^\epsilon = \{0\} \). If \( \deg (d\Gamma_i, D_k^\epsilon, 0) \neq (-1)^k \) for \( i = 1, 2 \), then \( 1 - \deg(d\Gamma_i, D_k^\epsilon, 0) \neq 1 + (-1)^{k-1} \). It is
well known fact that \( \chi(S_{k-1}^\epsilon) = 1 + (-1)^{k-1} \). From Corollary 1 in [S2] it follows
that \( \chi(B_i) = 1 - \deg(d\Gamma_i, D_k^\epsilon, 0) \). So, we have \( \chi(B_i) \neq \chi(S_{k-1}^\epsilon) \). From the above it follows that \( B_i \neq S_{k-1}^\epsilon \) for \( i = 1, 2 \). Fix \( \lambda_i \in S_{k-1}^\epsilon - B_i \) for \( i = 1, 2 \). Let \( \xi : [0, 1] \rightarrow S_{k-1}^\epsilon \) denote a continuous map such that \( \xi(0) = \lambda_1 \) and \( \xi(1) = \lambda_2 \).

Consider a composition \( \Phi \circ \xi : [0, 1] \rightarrow R \). It is obvious that \( (\Phi \circ \xi)(\lambda_1) \cdot (\Phi \circ \xi)(\lambda_2) < 0 \). So, from Krasnoselski theorem (see [K]) it follows that
\[
\text{Bif} (f) \cap \xi([0, 1]) \neq \emptyset.
\]
It is easy to verify that if \( \lambda_0 \in \text{Bif} (f) \), then \( t \cdot \lambda_0 \in \text{Bif} (f) \) for all \( t \in R \). So, our proof is completed. ■
In the last part of this section we turn to a case when a map $f$ is such that $\Phi(\lambda)$ is not necessary an homogeneous polynomial.

Definition 1.5. A map $f : \mathbb{R}^n \times \mathbb{R}^k \to \mathbb{R}^n$ is said to be an even map, if $\Phi(\lambda)$ is a polynomial such that $\Phi(-\lambda) = \Phi(\lambda)$.

The set of even maps will be denoted by Even $(n, k)$.

Fix $f \in $ Even $(n, k)$ and denote by $d$ the degree of $\Phi$. Choose any $\varepsilon > 0$. Define a map $\Lambda_\varepsilon : D^k_\varepsilon \to \mathbb{R}$ as follows

$$
\Lambda_\varepsilon(\lambda) = \Lambda_\varepsilon(\lambda_1, \ldots, \lambda_{k+1}) = \|\lambda\|^{d+2} \cdot \Phi \left( \frac{\varepsilon \lambda_1}{\|\lambda\|}, \ldots, \frac{\varepsilon \lambda_k}{\|\lambda\|} \right).
$$

Remark 1.2. Notice that $\Lambda_\varepsilon(\lambda)$ is a homogeneous polynomial and that $\text{sgn} \Lambda_\varepsilon(\lambda) = \text{sgn} \Phi(P(\lambda))$ for $\lambda \in S^k_\varepsilon$, where $P : S^k_\varepsilon \to D^k_\varepsilon$ is the projection given by the formula $P(\lambda) = (\lambda_1, \ldots, \lambda_k)$.

Define polynomials $\sum_{\varepsilon}^i : \mathbb{R}^{k+1} \to \mathbb{R}$ as follows

$$
\sum_{\varepsilon}^i(\lambda) = (-1)^i \Lambda_\varepsilon(\lambda) - (\lambda_1^2 + \cdots + \lambda_{k+1}^2)^{\frac{d+2}{2}} + 1,
$$

for $i = 1, 2$. By $d \sum_{\varepsilon}^i : \mathbb{R}^{k+1} \to \mathbb{R}^{k+1}$ we will denote the gradient of $\sum_{\varepsilon}^i$.

Proposition 1.5. For sufficiently small $\varepsilon_1 > 0$, if $\deg (d \sum_{\varepsilon}^i, D^k_{\varepsilon_1}, 0) \neq (-1)^{k+1}$ for $i = 1, 2$, then $\text{Bif} (f) \cap D^k_{\varepsilon_1} \neq \emptyset$; moreover the topological dimension of the set $\text{Bif} (f) \cap D^k_{\varepsilon_1}$ is equal to $k - 1$.

A proof of this proposition is a consequence of Proposition 1.4. and Remark 1.2.

2. Applications

In this section we will use the notations of the first section.

Consider a $C^1$-map $g : \mathbb{R} \times \mathbb{R}^n \times \mathbb{R}^k \to \mathbb{R}^n$ and assume that $g(t, x, \lambda)$ can be expressed in the form

$$
g(t, x, \lambda) = A(\lambda)x + \varphi(t, x, \lambda),
$$

where

1) $A(\lambda)$ is a $n \times n$-matrix such that $A(0) = \theta$;
2) $\varphi(t, 0, \lambda) = 0$ for all $(t, 0, \lambda) \in \mathbb{R} \times \mathbb{R}^n \times \mathbb{R}^k$,
3) $D_x \varphi(t, 0, \lambda) = 0$ for all $(t, 0, \lambda) \in \mathbb{R} \times \mathbb{R}^n \times \mathbb{R}^k$.

We are interested in describing the set of bifurcation points of the following boundary value problem

$$
(*) \quad \begin{cases}
\dot{x}(t) = g(t, x(t), \lambda) \\
x(0) = x(1).
\end{cases}
$$
Let us denote \( X = \{ x \in C^1([0,1]) : x(0) = x(1) \} \) and \( Y = C^0([0,1]) \). Define an operator \( F : X \times R^k \to Y \) by the formula

\[
F(x(t), \lambda) = L(\lambda)(x(t)) - \varphi(t, x(t), \lambda),
\]

where \( L(\lambda)(x(t)) = \dot{x}(t) - A(\lambda)x(t) \). Notice that zeroes of the operator \( f \) are in one-to-one correspondence with solutions of the problem (*).

Let \( f : R^n \times R^k \to R^n \) be the map defined by \( f(x, \lambda) = A(\lambda)x \). Now we are in a position to formulate the main theorem of our paper.

**Theorem 2.1.** If \( f \in \text{Ess } (n, k) \) and \( \varepsilon \) is a sufficiently small positive number, then

1) \( \text{Bif}(F) \cap D_\varepsilon^k = \Phi^{-1}(0) \cap D_\varepsilon^k \),
2) \( \text{Bif}(F) \cap S_{\varepsilon}^k \) is a \( (k-2) \)-dimensional manifold,
3) \( \chi(\text{Bif}(F) \cap S_{\varepsilon}^{k-1}) = \chi(\Phi^{-1}(0) \cap S_{\varepsilon}^{k-1}) = (1 + (-1)^k) \cdot (1 - \deg d\Phi) \).

**Proof:**

Notice that \( L(0) : X \to Y \) defined by \( L(0)(x(t)) = \dot{x}(t) \) is a Fredholm operator with Fredholm index 0 and that \( X = X_0 \oplus X_1 \) and \( Y = Y_0 \oplus Y_1 \), where

\[
X_0 = \ker L(0) = R^n = \{ \text{subspace of constant functions} \},
Y_0 = R^n = \{ \text{subspace of constant functions} \},
Y_1 = \text{im } L(0) = \{ x \in C^0[0,1] : \int_0^1 x(s) ds = 0 \},
\]

(see [M] for more details).

We begin with the Lyapunov-Schmidt reduction.

Let \( P_0(x) = \int_0^1 x(s) ds \) and \( P_1(x) = x - \int_0^1 x(s) ds \) denote the projections of \( Y \) onto \( Y_0, Y_1 \), respectively. Then the equation \( F(x, \lambda) = 0 \) is equivalent to the system of equations

\[
P_0(F(x_0 + x_1, \lambda)) = 0, \quad P_1(F(x_0 + x_1, \lambda)) = 0,
\]

where \( x = x_0 + x_1, \ x_0 \in X_0, \ x_1 \in X_1 \).

Notice that the map \( P_1 \circ F : X_0 \oplus X_1 \oplus R^k \to Y_1 \) is continuously differentiable near \( (0,0,0) \in X_0 \oplus X_1 \oplus R^k \), \( P_1 \circ F(0,0,0) = 0 \), and the Fréchet derivative of \( P_1 \circ F \) with respect to \( x_1 \) at \( (0,0,0) \), \( D_{x_1} P_1 \circ F(0,0,0) \) is an isomorphism of \( X_1 \) onto \( Y_1 \).

Therefore by the implicit function theorem, there is an open neighbourhood \( U \) of \( (0,0) \in X_0 \oplus R^k \) and \( x_1 \in C^1(U, X_1) \) such that the zeros of \( F \) near \( (0,0,0) \) are given by \( (x_0, x_1(x_0, \lambda), \lambda) \) for \( (x_0, \lambda) \in X_0 \oplus R^k \).

It is easy to see that \( x_1(x_0, \lambda) = 0(\|x_0\|) \) at \( x_0 = 0 \), uniformly for \( \lambda \) near 0.
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From the above it follows that zeros of $F$ are in one-to-one correspondence with zeros of a finite dimensional map $Q : U \rightarrow Y_0$ defined by the formula

$$Q(x_0, \lambda) = (P_0 \circ F)(x_0 + x_1(x_0, \lambda), \lambda).$$

It is not difficult to verify that $Q(x_0, \lambda)$ is a map of the form

$$Q(x_0, \lambda) = -A(\lambda)x_0 + \Psi(x_0, \lambda),$$

where $\Psi(0, \lambda) = 0$ and $D_{x_0} \Psi(0, \lambda) = 0$. Notice that $Q \in \text{Ess} (n, k)$.

The rest is a consequence of Propositions 1.1. and 1.2.

The next theorems give sufficient conditions for the existence of bifurcation points of the operator $F$ for more general class maps than the class $\text{Ess} (n, k)$.

Theorem 2.2. If $f \in \text{Hom} (n, k)$ and $\deg (d\Gamma_i, D^k_i, 0) \neq (-1)^k$ for $i = 1, 2$, then for any $\varepsilon_1 < \varepsilon \in \text{Bif} (F) \cap S^{k-1}_\varepsilon \neq \emptyset$. In particular, $0 \in \text{Bif} (F)$. Moreover the topological dimension of the set $\text{Bif} (F) \cap S^{k-1}_\varepsilon$ is equal to $k - 2$.

This theorem is a consequence of Proposition 1.4. A proof of this theorem is similar to the proof of Theorem 2.1.

Theorem 2.3. Let $f \in \text{Even} (n, k)$. Then for sufficiently small $\varepsilon$ if $\deg (d\sum_i D_i^{k+1}, 0) \neq (-1)^{k+1}$ for $i = 1, 2$, then $\text{Bif} (F) \cap D^k_\varepsilon \neq \emptyset$. Moreover the topological dimension of the set $\text{Bif} (F) \cap D^k_\varepsilon$ is equal to $k - 1$; in particular, $0 \in \text{Bif} (f)$.

This theorem is a consequence of Proposition 1.5. A proof of this theorem is similar to the proof of Theorem 2.1.

3. Examples

We shall remind well known results from singularity theory (see [E.L.]).

Let $\theta_n$ be the ring of germs of real analytic functions at $0 \in \mathbb{R}^n$. If $g_1, \ldots, g_n \in \theta_n$, let us denote by $\langle g_1, \ldots, g_n \rangle$ the ideal in $\theta_n$ generated by the elements $g_1, \ldots, g_n$.

For $g = (g_1, \ldots, g_n) : (\mathbb{R}^n, 0) \rightarrow (\mathbb{R}^n, 0)$ we put

$$Q(g) = \theta_n / \langle g_1, \ldots, g_n \rangle.$$ 

If $g$ is finite, in the sense that $Q(g)$ is finite dimensional real vector space, then $0 \in \mathbb{R}^n$ is isolated in $g^{-1}(0)$.

Consider the following boundary value problem

$$\begin{cases}
\dot{x}(t) = g(t, x(t), \lambda), \\
x(0) = x(1)
\end{cases}$$

(***)

For $\varepsilon_1 < \varepsilon \in \text{Bif} (F) \cap S^{k-1}_\varepsilon \neq \emptyset$.
and assume that the map \( g \) satisfies all the assumptions of the previous paragraph. So we can express \( g \) in the form \( g(t, x, \lambda) = A(\lambda)x + \varphi(t, x, \lambda) \). Theorems 2.1., 2.2., 2.3. show that it is enough to examine only the matrix \( A(\lambda) \).

Example 3.1. Assume that \( n = k = 3 \) and that the matrix \( A(\lambda) \) is of the form

\[
A(\lambda) = \begin{bmatrix}
\lambda_1 + \lambda_2, & \lambda_2 + \lambda_3, & \lambda_1 + \lambda_3 \\
\lambda_1 + \lambda_2 + \lambda_3, & \lambda_1 - \lambda_2, & 2 \cdot \lambda_1 - 3 \cdot \lambda_3 \\
\lambda_3, & \lambda_1, & 0
\end{bmatrix}
\]

Using a computer program we show that \( \text{deg} \left( d\Gamma_i, D^3_i, 0 \right) = 1 \) for \( i = 1, 2 \). From this it follows that \( \text{deg} \left( d\Gamma_i, D^3_i, 0 \right) \neq (-1)^3 \), so the assumption of Theorem 2.2. is fulfilled. Applying Theorem 2.2 we claim that there exists \( \varepsilon > 0 \) such that for any \( \varepsilon_1 < \varepsilon \) the intersection of the set of bifurcation points of the problem \( \dagger \ast \) with \( S^2_1 \) is not empty, in particular \( 0 \in \text{Bif} \left( F \right) \). Moreover the topological dimension of this intersection is equal to 1.

Example 3.2. Assume that \( n = k = 2 \) and that the matrix \( A(\lambda) \) is of the form

\[
A(\lambda) = \begin{bmatrix}
\lambda_1 - \lambda_2, & \lambda_1^2 - \lambda_2^2 \\
-\lambda_1 + 2 \cdot \lambda_2, & \lambda_1 \cdot \lambda_2 - \lambda_2^2
\end{bmatrix}
\]

Define a map \( f : \mathbb{R}^2 \times \mathbb{R}^2 \to \mathbb{R}^2 \) by \( f(x, \lambda) = A(\lambda)x \).

We will show that \( f \in \text{Ess} \left( 2, 2 \right) \). Using a computer program we show that \( \dim Q(\Psi) = 16 \), so from the results from singularity theory it follows that \( \Psi^{-1}(0) = \{0\} \), that is why \( f \in \text{Reg} \left( 2, 2 \right) \).

Computing the Brouwer topological degree (by computer) we obtain \( \text{deg} \ d\Phi = -2 \) and consequently

\[
\chi(\Phi^{-1}(0) \cap S^2_1) = (1 + (-1)^k) \cdot (1 - \text{deg} \ d\Phi) = (1 + (-1)^2) \cdot (1 - (-2)) = 6
\]

From this it follows that \( \Phi^{-1}(0) \neq \{0\} \), so \( f \in \text{Ess} \left( 2, 2 \right) \).

So from Theorem 2.1 it follows that \( \text{Bif} \left( F \right) \cap D^2_2 \) consist of exactly six intervals, which emanate from the origin.

References


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